



10th Power Analysis & Design Symposium

March 10th, 2021 - Worldwide (Virtual)

Measurement-based Characterization of Passive Electronic Components
by Martin Saliternig & Peter Maisel - MSPM Power

MSPM

HOT IDEAS FOR COOL PRODUCTS

power mechatronics

Measurement-based Characterization of Passive Electronic Components

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LIVE! 

10th Power Analysis & Design Symposium 2021

Wednesday, March 10, 2021



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- Absolute permeability μ_0 :
permeability in free space, magnetic constant

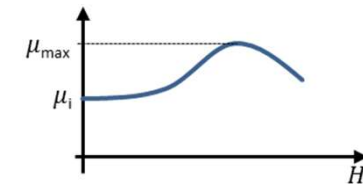
$$\mu_0 = 4\pi \cdot 10^{-7} \frac{N}{A^2}$$

- Relative permeability μ_r :
is the characterisation of magnetic materials for all purposes

$$\mu_r = \frac{\mu}{\mu_0} = \frac{1}{\mu_0} * \frac{B}{H}$$

- Initial permeability μ_i :
is the slope of the initial magnetization curve at the origin when the magnetic field strength H and the magnetic flux density B is very small.

- Maximum permeability μ_{max} :
is the maximum permeability along the initial magnetisation curve

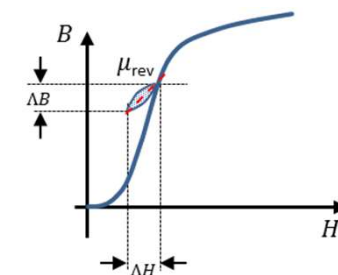


- Incremental permeability μ_Δ :
is the relative permeability for AC magnetisation with superimposed DC magnetisation

$$\mu_\Delta = \frac{1}{\mu_0} * \left(\frac{\Delta B}{\Delta H} \right)_{H_{DC}}$$

- Reversible permeability μ_{rev} :
is the limiting value of the incremental permeability for very low AC fields

$$\mu_{rev} = \lim_{\Delta H \rightarrow 0} \mu_\Delta$$



- Amplitude permeability μ_a :
is the relative permeability under alternating external fields H

$$\mu_a = \frac{1}{\mu_0} * \frac{B_{max}}{H_{max}}$$

- Effective permeability μ_e :
is the total permeability of an air gapped magnetic circuit .

$$\mu_e = \frac{\mu_i}{1 + \frac{l_g * \mu_i}{l_e}}$$

- Pulse permeability μ_p :
for pulse (or arbitrary) waveforms the pulse permeability is the ratio of flux density ΔB swing to the corresponding field strength ΔH .

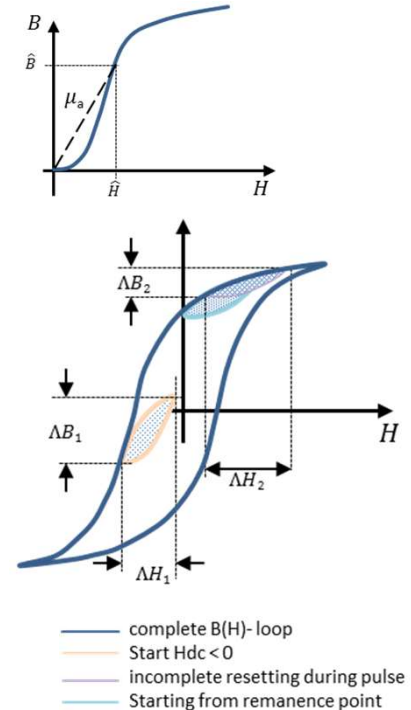
$$\mu_p = \frac{1}{\mu_0} * \frac{\Delta B}{\Delta H}$$

- Complex permeability $\underline{\mu}$:
the ratio of the flux density and the magnetic field strength is a complex number due to the phase shift between B and H in an alternating field.

$$\underline{\mu} = \mu' - j\mu''$$

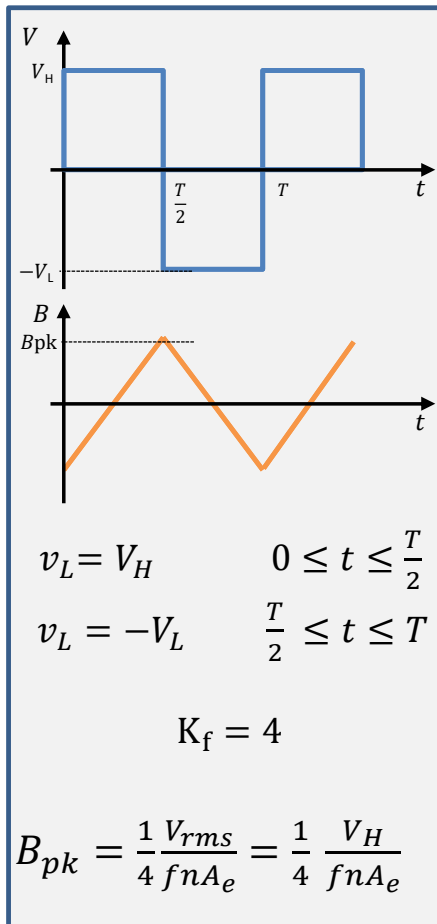
Frequently used: loss angle $\tan\delta$

$$\tan\delta = \frac{\mu'}{\mu''} = \frac{R}{\omega L}$$

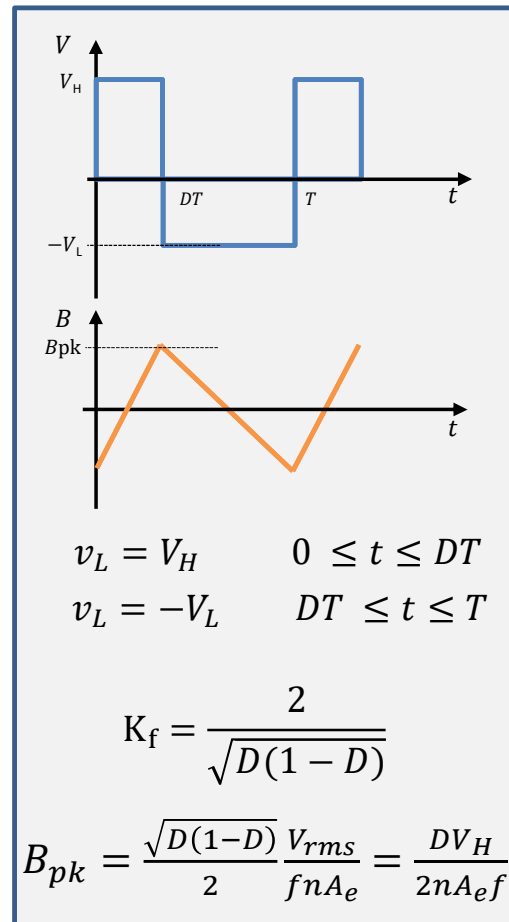


l_g : lenght of air gap
 l_e : lenght of magnetic path
 R : real resistance
 L : inductive part
 ω : circular frequency

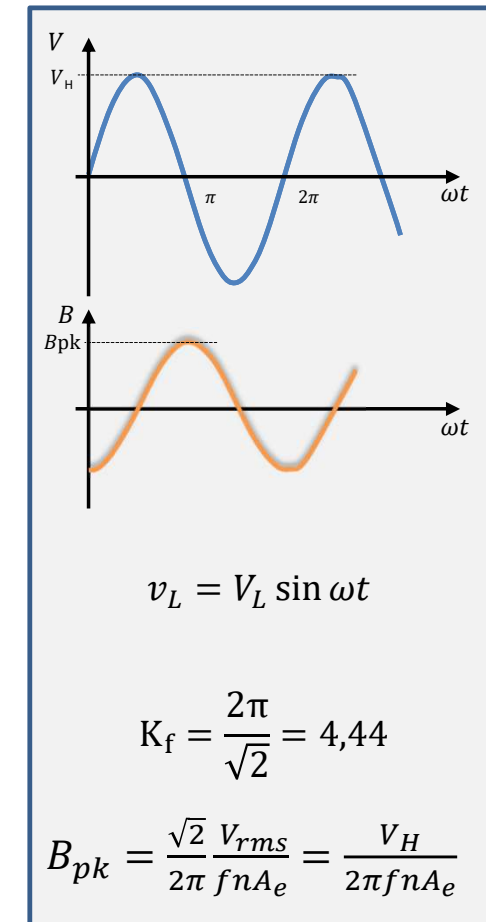
Square wave



Rectangular



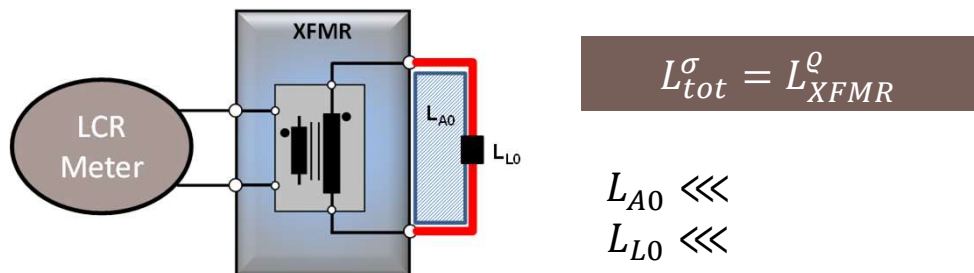
Sinusoidal



K_f : waveform coefficient
 f : frequency
 n : number of windings
 A_e : cross section area
 D : duty cycle
 B : flux density
 T : period

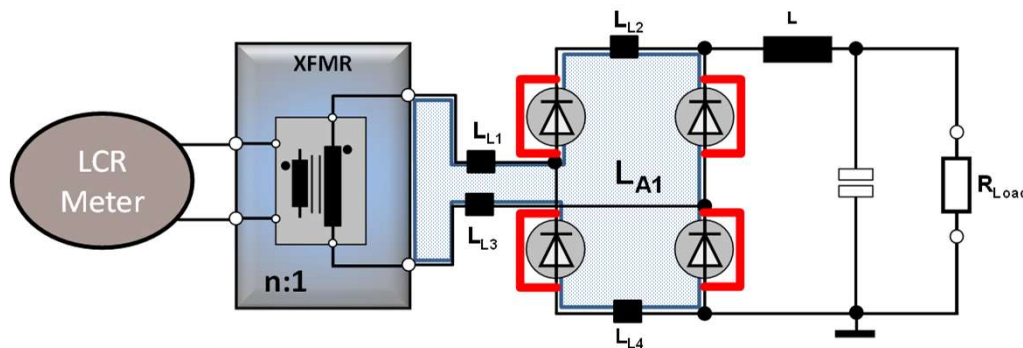
What is the effective leakage inductance?

Effective leakage inductance of the transformer



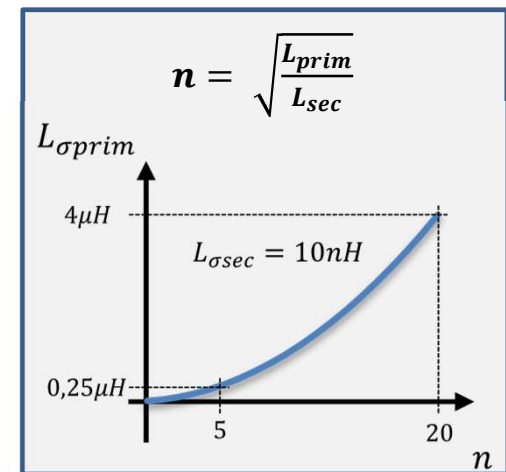
Rule of thumb
 $L_{LX} = 5..10nH/cm^{(1)}$
 $L_{Ax} \propto \sqrt{A}$

Effective leakage inductance in application circuit

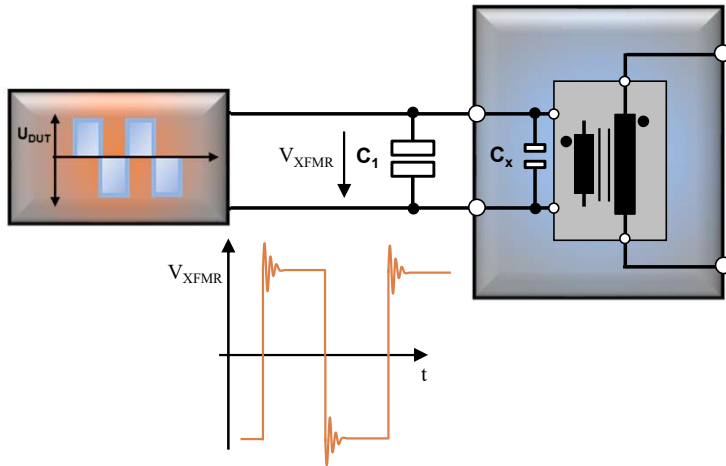


$$L_{appl}^e = L_{XFMR}^e + n^2 L_{sec}^e$$

$$L_{sec}^e = L_{L1} + L_{L2} + L_{L3} + L_{L4} + L_{A1}$$



(1) Typical values used on PCBs



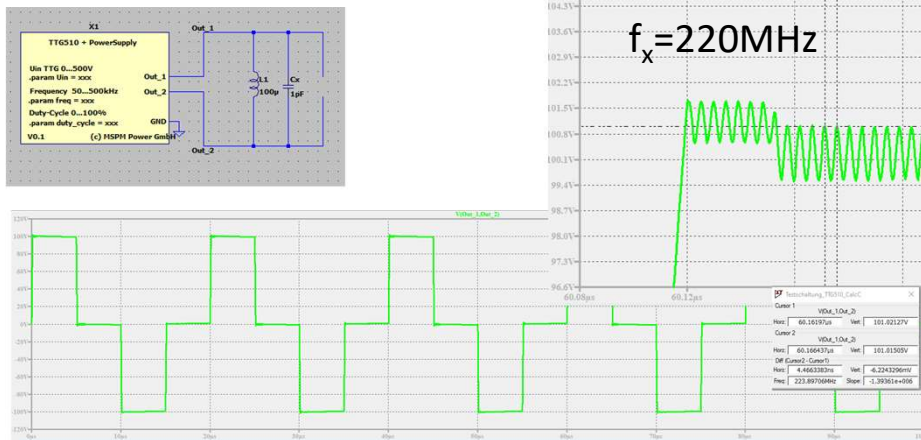
$$f_x = \frac{1}{2\pi\sqrt{LC_x}} \quad f_x \geq f_1$$

$$f_1 = \frac{1}{2\pi\sqrt{L(C_x + C_1)}}$$

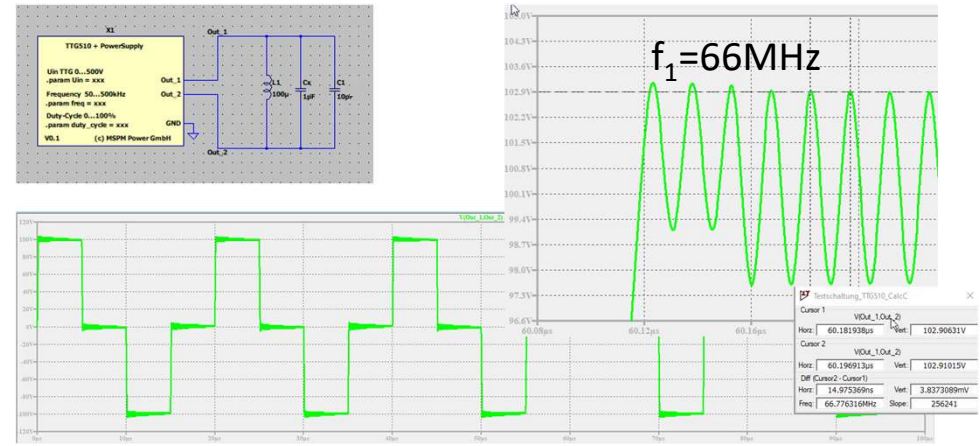
$$C_x = \frac{C_1}{\left(\frac{f_x}{f_1}\right)^2 - 1}$$

C_x ... Intra winding capacitance
 f_x ...frequency with winding capacitance
 C_1 ... reference capacitance
 f_1 ...frequency with winding capacitance and added reference capacitance

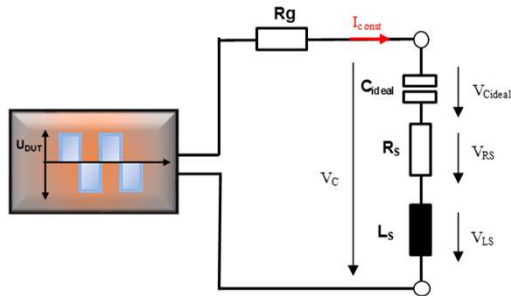
Frequency measurement with intra winding capacitance only:



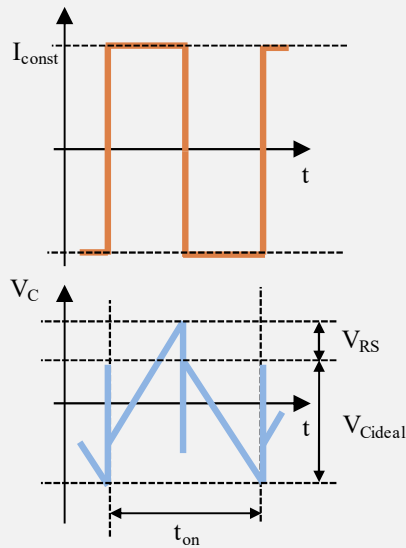
Frequency measurement with reference capacitance C_1 added:



Serial Equivalent Circuit Model



DC-Impedance



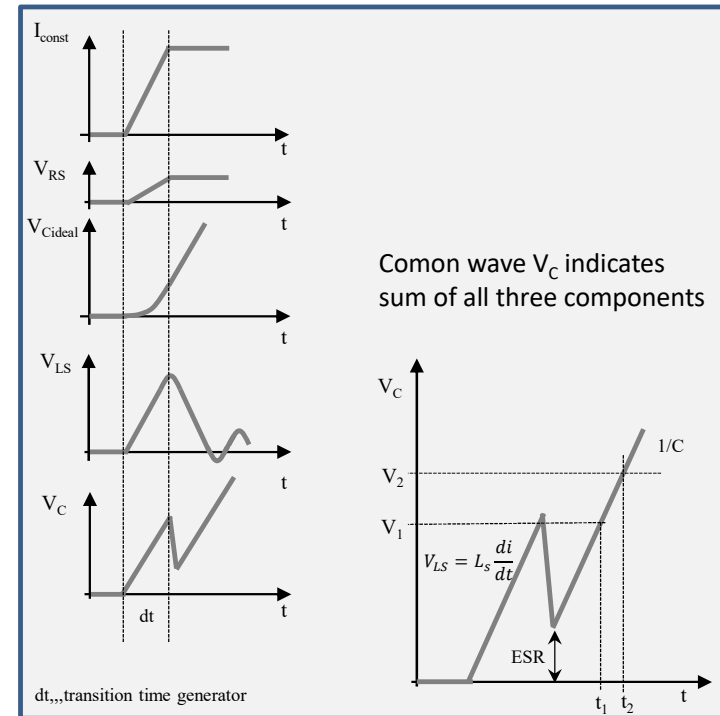
$$I_{const} = \frac{V_{out}}{R_g}$$

$$i = C \frac{du}{dt}$$

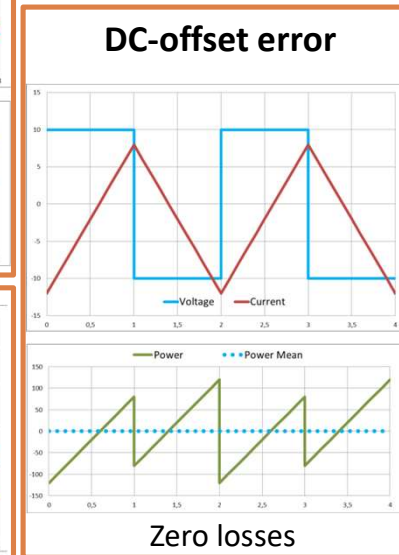
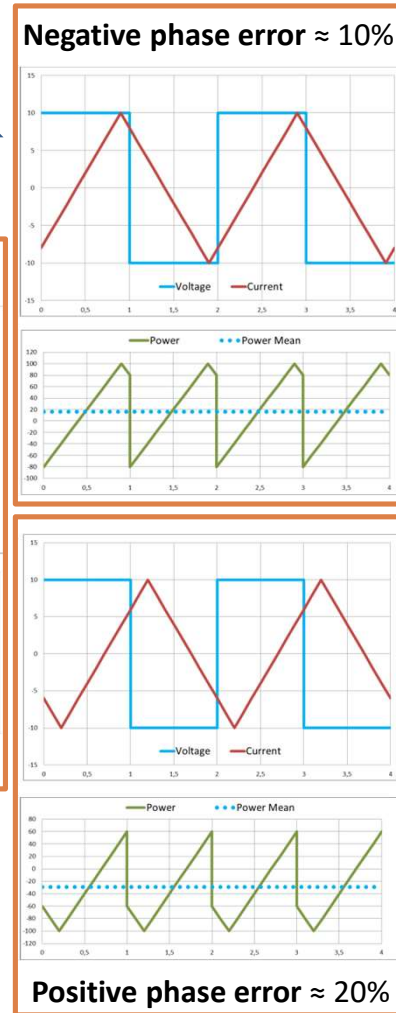
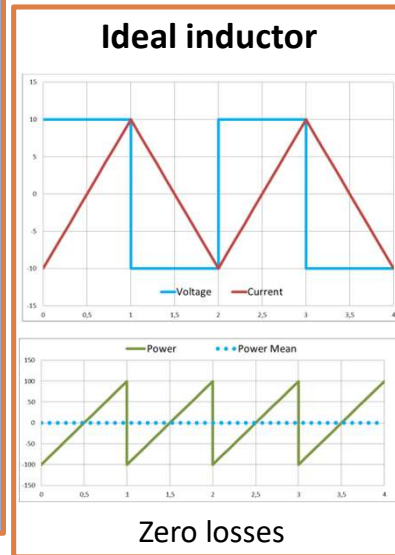
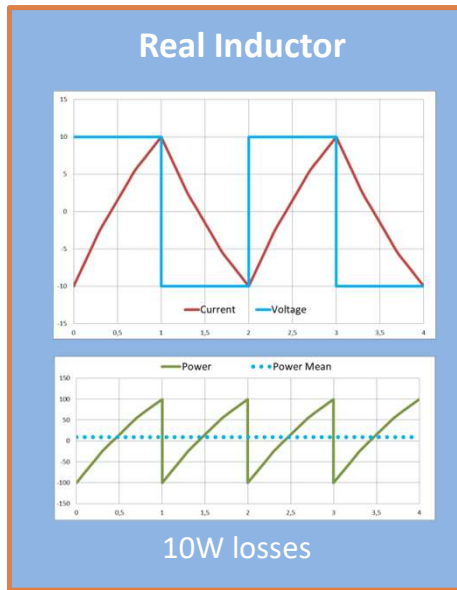
$$C = \frac{I_{const} (t_2 - t_1)}{(V_2 - V_1)}$$

$$R_s = \frac{V_{RS}}{2 * I_{const}}$$

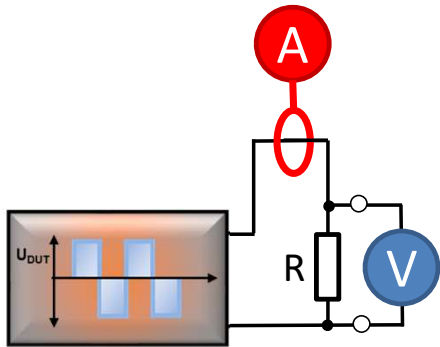
Current step response



DC-Impedance is more directly related to device behavior in many pulse power applications



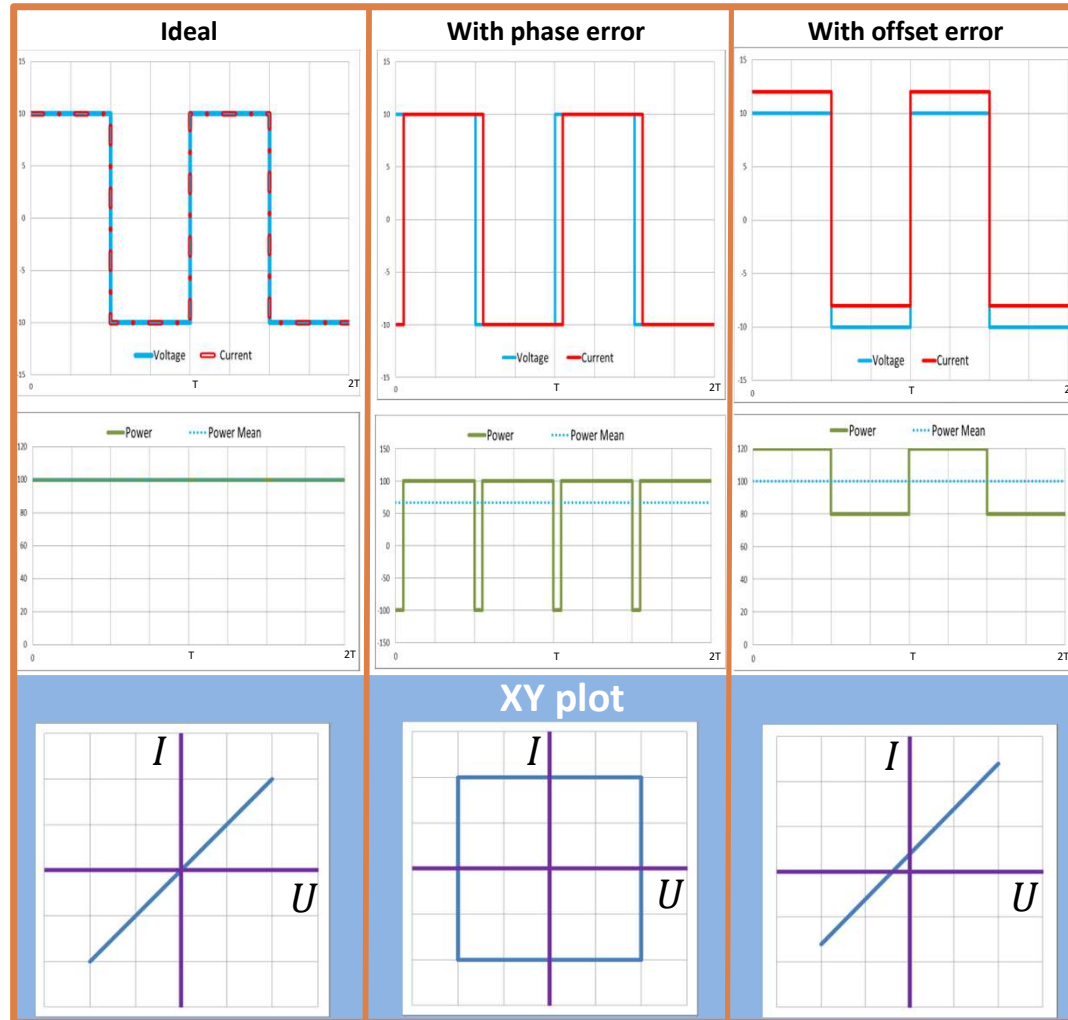
- Current
- Voltage
- Power
- - - Power Mean



5V/100mA (1kHz)
versus
500V/1A (100kHz)



Future?

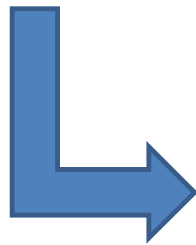


$$U = L \frac{di}{dt}$$

$$di = I_{PP}$$

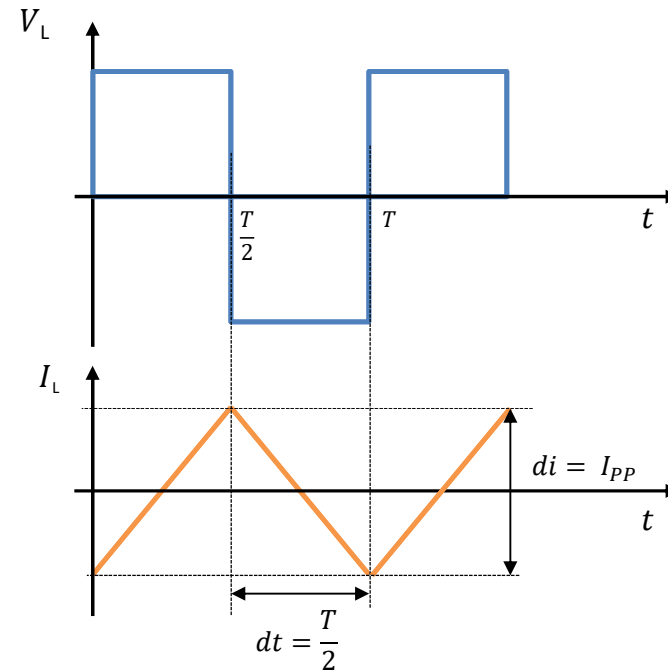
$$dt = \frac{T}{2}$$

simple scope functions

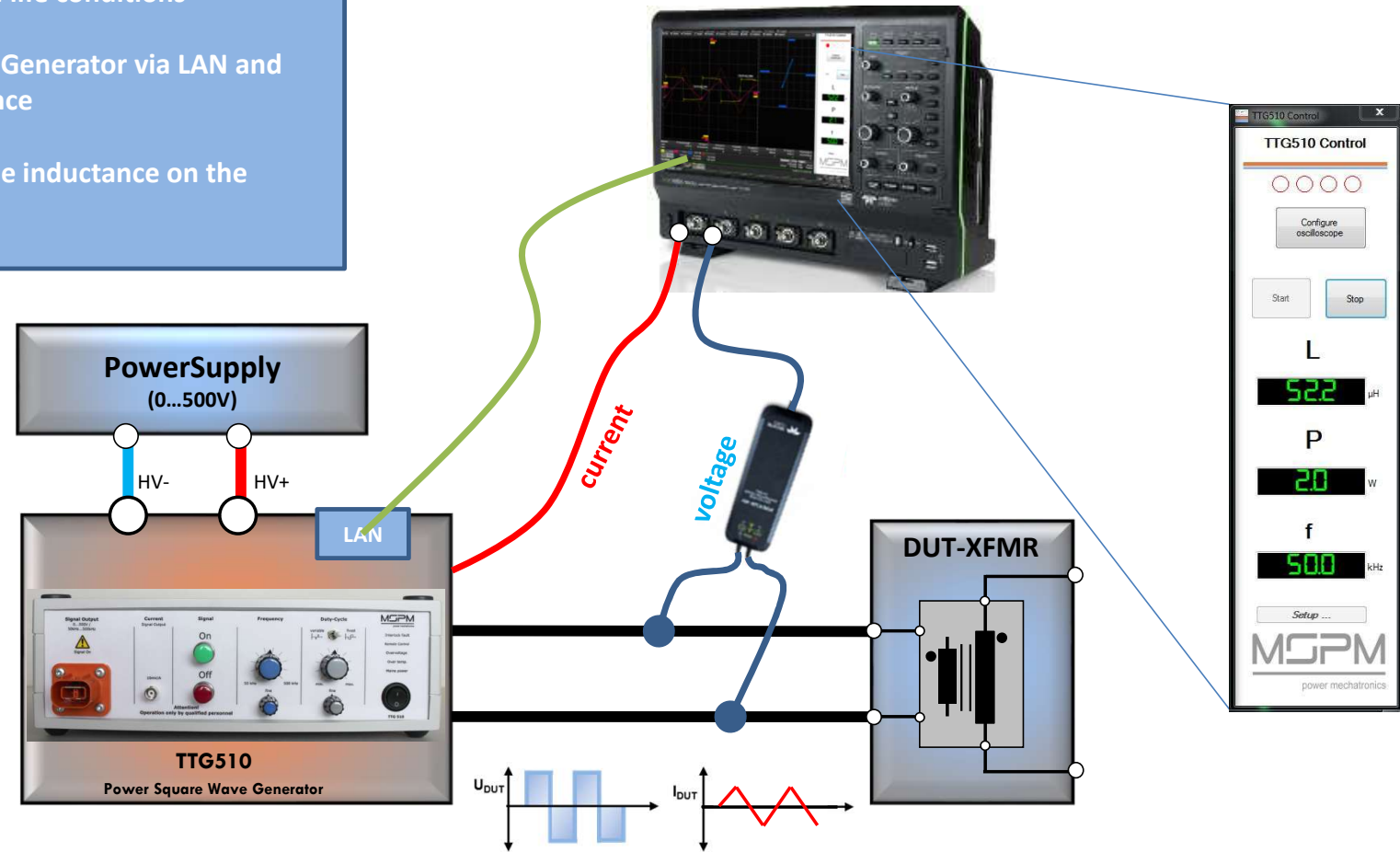


to inductance

$$L[H] = \frac{\Phi[Vsec]}{I_{PP}[A]} = \frac{V_{rms} T}{I_{PP} 2} = \frac{V_{rms}}{I_{PP}} \frac{1}{2f} = \frac{U dt}{di}$$



- Inductance measurement under real life conditions
- Scope is used to control the TTG510 Generator via LAN and analyze the measurement data at once
- MSPM App calculates and display the inductance on the screen



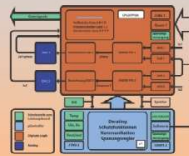
Hardware Development

Hardware Architecture
Hardware Design
Feasibility Study
Technology Assessment
Design Reviews
Electrical
Thermal
Mechanical
Device Development
Circuit Diagram and Layout



Digital Power

Application Software
Embedded Systems
Lab Automation
Digital Control
VHDL Design



TTG Series

Universal Square Wave Generator

Determination of power losses in magnetic materials
Identification of saturation limits in magnetics
Identification of the parasitic capacitances
Source for inductive power transmission
Source to inject ripple current into components

MSPM Power GmbH
Lenzenbergstrasse 9
91074 Herzogenaurach
Germany

Telefon + 49 911 2170 8333
Telefax + 49 911 9232 37 85
Email: info@mspm-power.de

www.mspm-power.de

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Addon: Saturation detection

